An analytic BPHZ theorem for Regularity Structures Paths to, from and in renormalization - Potsdam

Ajay Chandra - Joint work with Martin Hairer (Warwick)

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• **Reg. Struct. approach:** Lift concrete fixed point problem to an abstract fixed point problem in a space of jets of (generalized) Taylor polynomials.

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 Reg. Struct. approach: Lift concrete fixed point problem to an abstract fixed point problem in a space of jets of (generalized) Taylor polynomials. Looking at Φ⁴₃ we have

$$\varphi = G * \left[-\varphi^3 + \zeta \right] \quad \Rightarrow \quad \frac{\Phi = \mathcal{G} * \left[-\Phi^3 + \Xi \right]}{\Phi(z) = ! + \Phi_1(z)\mathbf{1} - \mathbf{\hat{\vee}} + \Phi_{\mathbf{\hat{\vee}}}(z)\mathbf{\hat{\vee}} + \cdots}$$

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• Passage from abstract to concrete: Encoded by a model $Z = (\Pi, \Gamma)$. Here $\Pi = {\{\Pi_x\}}_{x \in \mathbb{R}^d}$, all of the Π_x 's map an indeterminant τ to a concrete element of $\mathcal{S}'(\mathbb{R}^d)$. Π and Γ need to satisfy fairly restrictive algebraic and analytic conditions.

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$$\varphi = G * \left[-\varphi^3 + \zeta \right] \quad \Rightarrow \quad \frac{\Phi = \mathcal{G} * \left[-\Phi^3 + \Xi \right]}{\Phi(z) = ! + \Phi_1(z)\mathbf{1} - \mathbf{\hat{Y}} + \Phi_{\mathbf{\hat{Y}}}(z)\mathbf{\hat{Y}} + \cdots$$

Passage from abstract to concrete: Encoded by a model Z = (Π, Γ). Here Π = {Π_x}_{x∈R^d}, all of the Π_x's map an indeterminant τ to a concrete element of S'(R^d). Π and Γ need to satisfy fairly restrictive algebraic and analytic conditions. Π_x[τ] is the "homogenous" x -centered incarnation of the space-time distribution represented by the indeterminant τ

Key Bound: $|(\Pi_x[\tau])(\theta_{x,\lambda})| \lesssim \lambda^{|\tau|}$ uniformly for λ small.

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- Let Π^ε be the "naive" way of mapping symbols to convolutions of ζ_ε. We denote by Z^ε = (Π^ε, Γ^ε) the canonical lift of ζ_ε. In general we cannot set (Π^ε_x[τ])(•) := (Π^ε[τ])(•).

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 $(\Pi_x^{\epsilon}\tau)(\bullet) = (\Pi^{\epsilon}[\cdot](\bullet) \otimes \Pi^{\epsilon}[\cdot](x))(\mathbf{1} \otimes \mathcal{A}_+) \Delta \tau$

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where $\Delta : \mathcal{H} \mapsto \mathcal{H} \otimes \mathcal{H}_+$ is a comodule coproduct and $\mathcal{A}_+ : \mathcal{H}_+ \mapsto \mathcal{H}$ is a pseudo-antipode.

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Positive renormalization counterterms are not designed to kill the divergences that appear in the individual terms of perturbation theory. Instead they enforce the property of *homogeneity*.

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Positive renormalization counterterms are not designed to kill the divergences that appear in the individual terms of perturbation theory. Instead they enforce the property of *homogeneity*. This property is what allows the fixed point relations for non-perturbative parts of the expansion to be closed.

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 Within the framework of regularity structures the issue of UV divergences appears when we try to show the convergence of the Z^ε.

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 $|(\Pi_x^{\epsilon} \tau)(\theta_{x,\lambda})| \lesssim \lambda^{|\tau|}$ uniformly for λ and ϵ small.

 UV divergences will be handled by the negative renormalizations. These divergences already occur on the level of Π^ε so it is natural to the define the negative renormalizations on this object.

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Here $\hat{\Delta} : \mathcal{H} \mapsto \mathcal{H}_{-} \otimes \mathcal{H}$, and $\mathcal{A}_{-} : \mathcal{H}_{-} \mapsto \mathcal{H}$ is a pseudo-antipode.

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 The Π^ε will "converge" - but this is only a "perturbative" statement (term by term), in order to have a non-perturbative statement we need convergence in the space of models! Need to build the maps Π^ε_x.

 $\hat{\mathsf{\Pi}}_x^\epsilon[\tau](\bullet) = \Big(\mathsf{\Pi}^{\mathbb{E},\epsilon}[\cdot](0) \otimes \mathsf{\Pi}^\epsilon[\cdot](\bullet) \otimes \mathsf{\Pi}^\epsilon[\cdot](x)\Big) (\mathcal{A}_- \otimes \mathbf{1} \otimes \mathcal{A}_+) (\mathbf{1} \otimes \Delta) \hat{\Delta} \tau.$

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$$\hat{\Pi}^{\epsilon}_{X}[au](ullet) = \Big(\mathbf{\Pi}^{\mathbb{E},\epsilon}[\cdot](0)\otimes\mathbf{\Pi}^{\epsilon}[\cdot](ullet)\otimes\mathbf{\Pi}^{\epsilon}[\cdot](x) \Big) (\mathcal{A}_{-} \otimes \mathbf{1} \otimes \mathcal{A}_{+}) (\mathbf{1} \otimes \Delta) \hat{\Delta} au.$$

• Our point of departure: We have inserted all the counterterms we think we need but it is not immediate that we have the bound:

 $|(\Pi_x^{\epsilon} \tau)(\theta_{\lambda,x})| \lesssim \lambda^{|\tau|}$ uniformly for ϵ, λ small, almost surely in ζ .

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For all pand τ with $|\tau| < 0$, $\mathbf{E}[|(\Pi_0^{\epsilon} \tau)(\theta_{0,\lambda})|^p] \lesssim \lambda^{p(|\tau|+\kappa)}$ uniformly for λ, ϵ small.

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• Moment estimate can be expressed as a sum of graphs. We expand A_+ and A_- as a "double forest" formula, perform a multiscale expansion, and then reorganize forests in a scale-dependent manner.

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- Moment estimate can be expressed as a sum of graphs. We expand \mathcal{A}_+ and \mathcal{A}_- as a "double forest" formula, perform a multiscale expansion, and then reorganize forests in a scale-dependent manner.
 - Extension of Feldman-Magnen-Rivasseau-Seneor '85 multiscale techniques, organizes both positive and negative renormalization counterterms.

$$\hat{\Pi}_{x}^{\epsilon}[\tau](\bullet) = \Big(\Pi^{\mathbb{E},\epsilon}[\cdot](0) \otimes \Pi^{\epsilon}[\cdot](\bullet) \otimes \Pi^{\epsilon}[\cdot](x) \Big) (\mathcal{A}_{-} \otimes \mathbf{1} \otimes \mathcal{A}_{+}) (\mathbf{1} \otimes \Delta) \hat{\Delta} \tau.$$

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 - Extension of Feldman-Magnen-Rivasseau-Seneor '85 multiscale techniques, organizes both positive and negative renormalization counterterms.
 - Generalizes bound found in Hairer-Quastel.

$$\left|\int \mathrm{d}x_{\mathcal{V}} \ H(x_{\mathcal{V}})\right| = \left|\sum_{\mathbf{j}\in\mathcal{N}}\int \mathrm{d}x_{\mathcal{V}} \ H^{\mathbf{j}}(x_{\mathcal{V}})\right|$$

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Want to bound, for a fixed $T \in \mathcal{T}$,

$$\sum_{\substack{\ell \in \mathcal{L}_T \\ \ell(\mathbf{v}_*) \geq \alpha}} \left(\prod_e 2^{\ell(e)a_e} \right) \left(\prod_{\mathbf{v} \in T^\circ} 2^{-|\mathfrak{s}|\ell(\mathbf{v})(d_{\mathbf{v}}-1)} \right).$$

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A rough sketch of how counterterms are organized.

 $\sum_{\mathcal{F} \in \mathbb{F}} \sum_{\mathcal{C} \in \mathfrak{G}_{\mathcal{F}}} \int \mathrm{d} x_{\mathcal{V}} \ \mathcal{H}_{\mathcal{C}, \mathcal{F}}(x_{\mathcal{V}})$

Where

$\mathbb{F} = \begin{array}{c} \text{collection of all forests} \\ \text{of acceptable divergent structures} \end{array}$

$\mathfrak{C}_{\mathcal{F}} = \begin{array}{c} \text{the collection of all acceptable cut sets} \\ \text{which do not include any cut} \\ \text{falling into an element of } \mathcal{F} \end{array}$

A rough sketch of how counterterms are organized.

 $\sum_{\mathcal{F} \in \overline{\mathbb{F}}} \sum_{\mathcal{C} \subseteq \overline{\mathfrak{C}_{\mathcal{F}}}} \int \mathrm{d} x_{\mathcal{V}} \ H_{\mathcal{C},\mathcal{F}}(x_{\mathcal{V}})$

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$$\overline{\mathfrak{C}_{\mathcal{F}}} = \begin{array}{l} \text{the set of all cut positions} \\ \text{except for those that fall} \\ \text{into an element of } \mathcal{F} \end{array}$$

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- Given an edge $e = (e_-, e_+) \in \overline{\mathfrak{C}}$, we want to harvest the positive renormalization corresponding to e if

 $j_{\{e_+,0\}} > j_{\{e_-,0\}}.$

- To handle positive renormalizations we imagine there is a fictitious edge between each vertex and 0 which is also given a scale index. We now prescribe algorithms which for a given scale assignment **j** tell us which renormalization cancellations we want to harvest.
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$$j_{\{e_+,0\}} > j_{\{e_-,0\}}.$$

• The situation for negative renormalizations is more complicated. For now we forget about positive renormalizations. Define "projection operator" $P^{j}: \overline{\mathbb{F}} \mapsto \overline{\mathbb{F}}$ by setting

$$P^{\mathbf{j}}[\mathcal{F}] = \begin{cases} & \text{the largest scale index among the} \\ & \text{external edges (mod } \mathcal{F}) \text{ of } \mathcal{T} \\ \mathcal{T} \in \mathcal{F} : & \text{is greater than or equal to} \\ & \text{the minimum scale index among the} \\ & \text{internal edges (mod } \mathcal{F}) \text{ of } \mathcal{T}. \end{cases} \end{cases}$$

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• $P^{\mathbf{j}}$ is called a forest projection because it satisfies $(P^{\mathbf{j}})^2 = P^{\mathbf{j}}$. Define $\mathfrak{M} := \begin{cases} \mathbb{M} \subseteq \overline{\mathbb{F}} : & \exists \mathcal{S} \in \overline{\mathbb{F}}, \ \mathbf{j} \in \mathcal{N} \text{ such that} \\ P^{\mathbf{j}}[\mathcal{S}] = \mathcal{S} \text{ and } \mathbb{M} = (P^{\mathbf{j}})^{-1}[\mathcal{S}] \end{cases} \end{cases}$

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$$\begin{split} \mathfrak{M} &:= & \left\{ \mathbb{M} \subseteq \overline{\mathbb{F}} : \begin{array}{c} \exists \mathcal{S} \in \overline{\mathbb{F}}, \ \mathbf{j} \in \mathcal{N} \text{ such that} \\ P^{\mathbf{j}}[\mathcal{S}] &= \mathcal{S} \text{ and } \mathbb{M} = (P^{\mathbf{j}})^{-1}[\mathcal{S}] \end{array} \right\} \\ \mathcal{N}_{\mathbb{M}} &:= & \left\{ \mathbf{j} \in \mathcal{N} : \begin{array}{c} \exists \mathcal{S} \in \overline{\mathbb{F}} \text{ such that} \\ P^{\mathbf{j}}[\mathcal{S}] &= \mathcal{S} \text{ and } \mathbb{M} = (P^{\mathbf{j}})^{-1}[\mathcal{S}] \end{array} \right\}. \end{split}$$

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• \mathfrak{M} is a collection of "intervals" of the poset $\overline{\mathbb{F}}$. Idea: Summing $\mathcal{F} \in \mathbb{M}$ for fixed $\mathbb{M} \in \mathfrak{M}$ renormalizes the divergences that appear for coalesence trees determined by $\mathbf{j} \in \mathcal{N}_{\mathbb{M}}$ on subsets of graph vertices where the elements of $Min(\mathbb{M})$ are contracted:

$$\sum_{\in \mathcal{N}_{\mathbb{M}}} \left| \sum_{\mathcal{F} \in \mathbb{M}} \int \mathrm{d} x_{\mathcal{V}} \ \mathcal{H}^{\mathbf{j}}_{\varnothing,\mathcal{F}}(x_{\mathcal{V}}) \right| < \infty$$

$$\begin{split} \mathfrak{M} &:= & \left\{ \mathbb{M} \subseteq \overline{\mathbb{F}} : \begin{array}{c} \exists \mathcal{S} \in \overline{\mathbb{F}}, \ \mathbf{j} \in \mathcal{N} \text{ such that} \\ P^{\mathbf{j}}[\mathcal{S}] &= \mathcal{S} \text{ and } \mathbb{M} = (P^{\mathbf{j}})^{-1}[\mathcal{S}] \end{array} \right\} \\ \mathcal{N}_{\mathbb{M}} &:= & \left\{ \mathbf{j} \in \mathcal{N} : \begin{array}{c} \exists \mathcal{S} \in \overline{\mathbb{F}} \text{ such that} \\ P^{\mathbf{j}}[\mathcal{S}] &= \mathcal{S} \text{ and } \mathbb{M} = (P^{\mathbf{j}})^{-1}[\mathcal{S}] \end{array} \right\}. \end{split}$$

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Similar to overlapping divergences, the positive and negative renormalizations we need simultaneously are non-overlapping in phase-space so both can be harvested at the same time. By using a hierarchy of distributional norms we can deal with nested divergences through an inductive procedure.
Alay Chandra (Warvick)

Theorem (C. - Hairer)

For subcritical perturbations of the heat equation driven by noise no worse than space-time white noise (with good cumulant bounds) there is a renormalization scheme for the canonical model yielding renormalized models \hat{Z}^{ϵ} which for every τ , and each $p \in \mathbf{N}$ satisfy the bound

 $\mathbf{E}\left[\left|(\hat{\Pi}_{0}^{\epsilon}\tau)(\theta_{0,\lambda})\right|^{p}\right] \lesssim \lambda^{p(|\tau|+\kappa)} \text{ uniformly for } \lambda, \epsilon \text{ small.}$

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Thanks for listening!